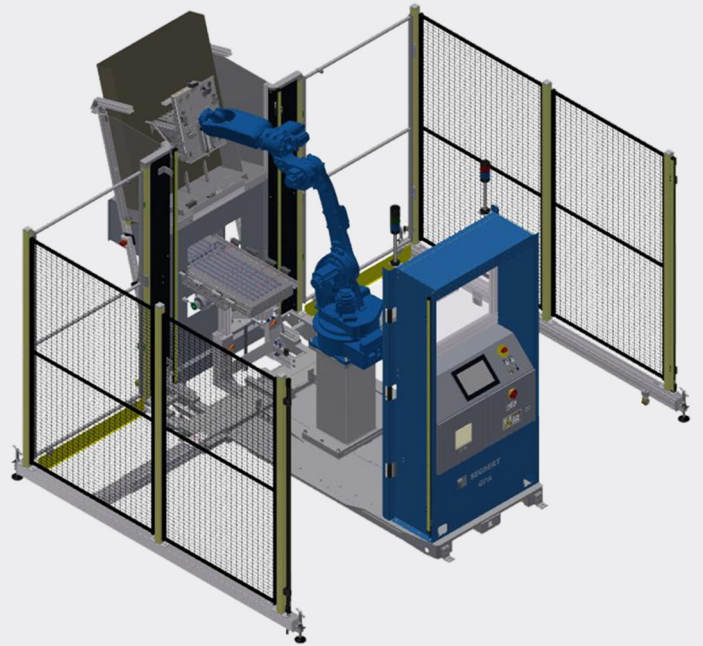


## GPA-25

### Palletizing robot

with fork gripper

6-axis-robot for dynamic palletizing and depalletizing on up to 2 pallets



#### Technical Specifications

<b>Products</b>	Open cardboard boxes, boxes, trays, and loose products such as paper stacks, magazines and other packages	
<b>System</b>	6-axis-robot	
<b>Product width</b>	max.	260 mm
	min.	150 mm
<b>Product length</b>	max.	380 mm, back length, with slip sheet, without slip sheet also longer
	min.	150 mm
<b>Product height</b>	max.	230 mm
	min.	35 mm
<b>Load capacity</b>	max.	12 kg*
<b>Pallet formats</b>	800 x 1200 mm, 1000 x 1200 mm, 40 x 48", 1165 x 1165 mm, 45 x 45" (other pallet formats possible)	
<b>Pallet height</b>	max.	1600 mm, incl. pallet (euro pallet)*
<b>Empty pallet height</b>	140 mm (min.) – 160 mm (max.)	
<b>Speed</b>	max.	6 cycles/min.*
<b>Drive</b>	6 controlled Servo axes	
<b>Voltage</b>	3 x 380 – 440 VAC, 50/60 Hz	
<b>Power consumption</b>	approx.	3 kVA
<b>Fuse</b>	3 x 16 A, slow-blow fuse	
<b>Air pressure</b>	min.	6 bar
<b>Air consumption</b>	depending on gripping device	
<b>Control</b>	IPC with RobAdmin palletizing program as a configuration interface for setting the package and pallet sizes and the layer patterns	

\*The data given is interdependent with product dimensions, pallet format, pallet height, speed, gripping tool, column height and number of slip sheets.

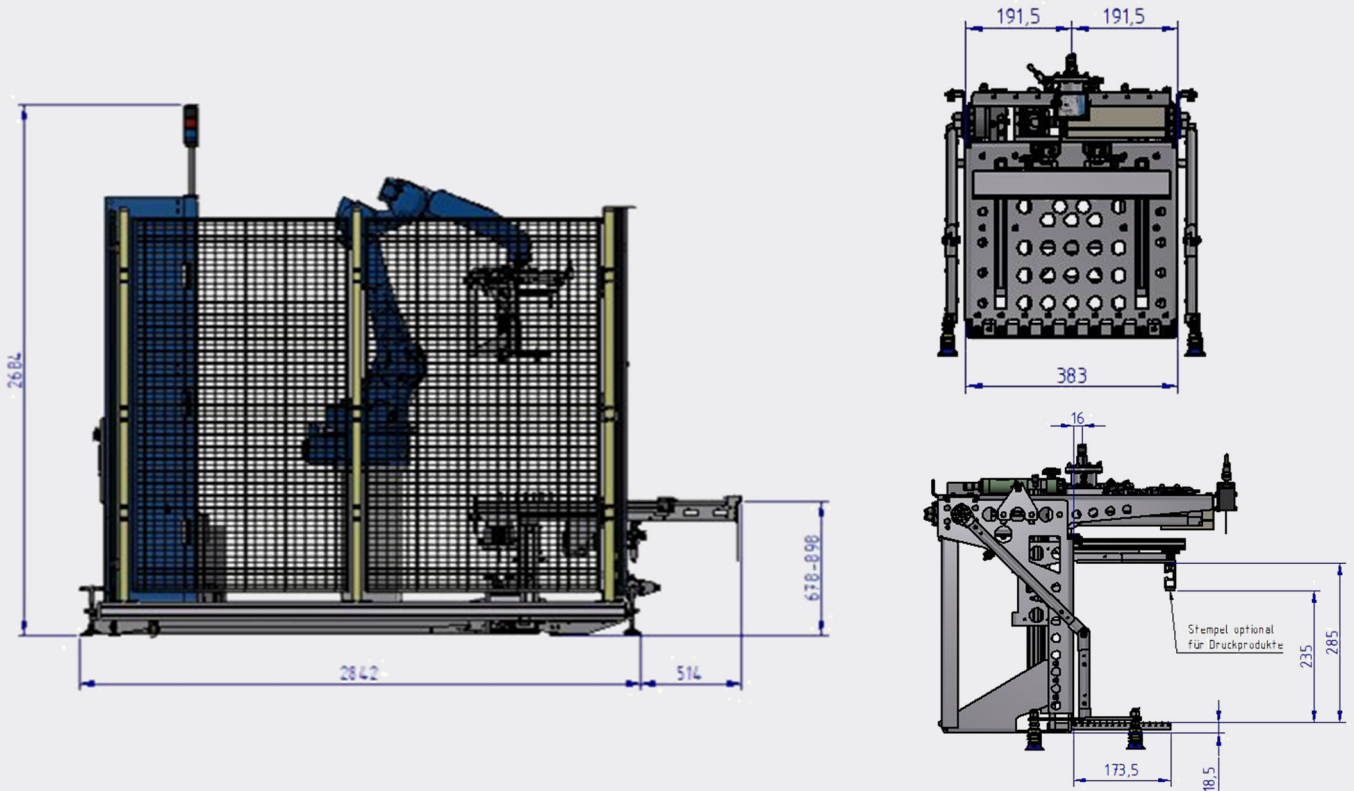
Color scheme as shown (see above).

# SEGBERT

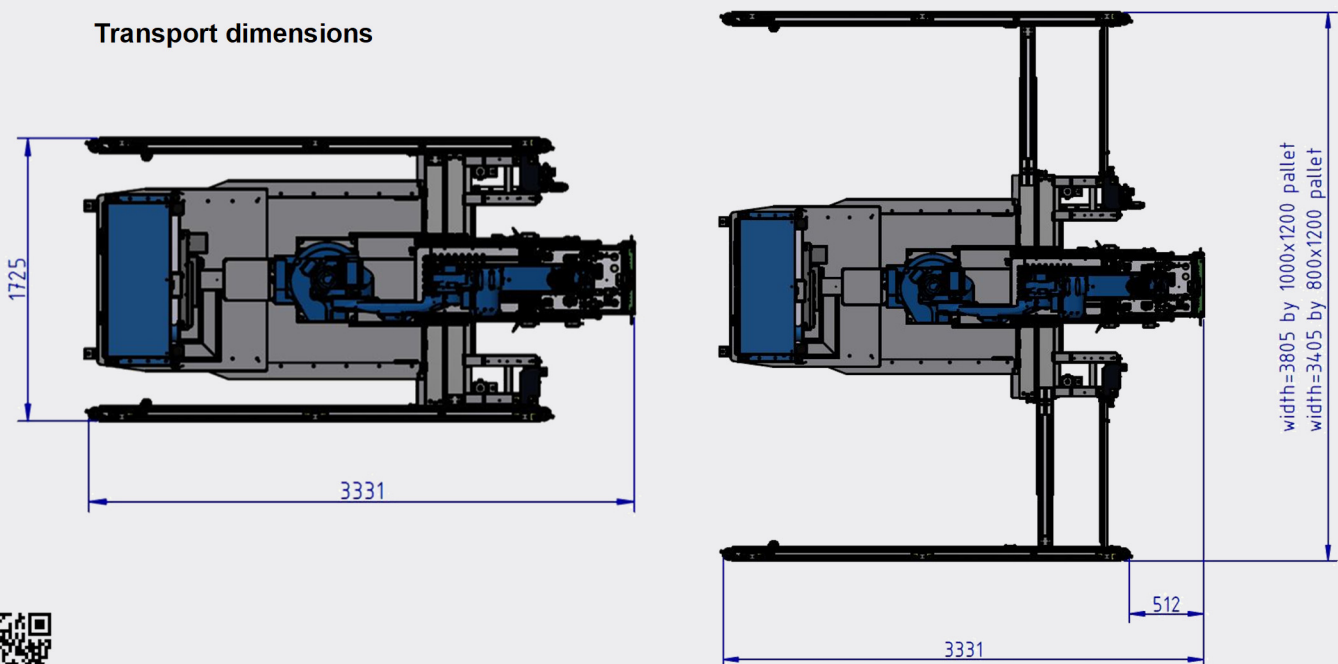
## PALLETIZING & AUTOMATION

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### Transport dimensions



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Komplementär: Segbert Verwaltungsgesellschaft mbH Sitz: Ahaus Registergericht: Coesfeld, HRB 4251  
Geschäftsführer: Klaus Segbert